

The Geometry of Imprecise Inference

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I am Professor Emeritus in the Department of Mathematics and Statistics at the



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- My recent graduates:
 - Osama Bataineh, PhD 2012
 - Chel Hee Lee, PhD 2014
- Two current students
- Research supported by the Natural Sciences and Engineering Research Council of Canada





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- Exponential family
- Dual manifold
- Lower envelope theorem
- Linear updating

Examples

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$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

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$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$
$$\log \frac{P(B|A)}{P(A)} = \log P(B|A) - \log P(B)$$

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$$\log \frac{P(B|A)}{P(A)} = \log P(B|A) - \log P(B)$$
$$\log \frac{P(A|B)}{P(A^c|B)} = \log \frac{P(B|A)}{P(B|A^c)} + \log \frac{P(A)}{P(A^c)}$$

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$$\log \frac{P(A|B)}{P(A)} = \log \frac{P(B|A)}{P(B|A^{c})} + \log \frac{P(A^{c}|B)}{P(A^{c})}$$

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$$\log \frac{P(A|B)}{P(A)} = \log \frac{P(B|A)}{P(B|A^{c})} + \log \frac{P(A^{c}|B)}{P(A^{c})}$$
$$\log \frac{d\Pi_{y}}{d\Pi_{0}}(\theta) = \log \frac{dP_{\theta}}{dP_{0}}(y) + \text{something else}$$

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$$\log \frac{P(A|B)}{P(A)} = \log \frac{P(B|A)}{P(B|A^{c})} + \log \frac{P(A^{c}|B)}{P(A^{c})}$$
$$\log \frac{d\Pi_{y}}{d\Pi_{0}}(\theta) = \log \frac{dP_{\theta}}{dP_{0}}(y) + \text{something else}$$
$$\log \frac{d\Pi_{y}}{d\Pi_{0}}(\theta) = \theta^{\mathsf{T}} \mathbf{v}(y) - I(P_{0}|P_{\theta}) - \psi(y)$$

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An **exponential family of distributions** can be represented in terms of the vector space of minimal sufficient statistics (i.e. functions on the observation space.) The manifold of distributions \mathcal{M} maps uniquely unto a tangent

space \mathcal{L} . spanned by the minimal sufficient statistics.



 $\log \frac{dP_{\theta}}{dP_{0}} = \theta v - I(P_{0}|P_{\theta})$

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A prior distribution is a distribution on \mathcal{L} . An exponential family of priors can be expressed in terms of the space of linear functions on \mathcal{L} .

This dual space will include the evaluation functional $v \mapsto v(y)$, and thus will include all possible posteriors from any prior in the family.

$$\log \frac{d\Pi_y}{d\Pi_0}(v) = v(y) - I(P_0|P_v) - \psi(y)$$



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Bayes' theorem Exponential family Dual manifold Lower envelope theorem Linear updating Examples

The lower envelope theorem says that a lower prevision can be expressed as the infimum over a set of linear previsions. This means that an imprecise prior can represented by a set of precise priors.

In the expression

$$\log \frac{d\Pi_y}{d\Pi_0}(\boldsymbol{\theta}) = \boldsymbol{\theta}^{\mathsf{T}} \mathbf{v}(y) - I(P_0|P_{\boldsymbol{\theta}}) - \psi(y)$$

the first two terms on the right do not depend on the prior, and thus would translate all priors in the same way. The third term does not depend on the model parameter θ .

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Normal family with known variance.



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Censored exponential model with gamma prior



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